

| | | Remote | Base | |
|-----------|----------------|-----------------------------------------------------|----------------------|---------------------------------------------------|
| Type code | DeviceNet | RCD33T-211-DNC | Type code DeviceNet | RCD33E-211-DNC |
| Drive vo | oltage | 24V ± 1.5V DC | Operational voltage | 24V DC ± 5% (incl. Ripple) |
| Drive cu | urrent | ≦ 2A | Current consumption | ≦ 3A |
| Operation | ng distance | 35mm | Communication | DeviceNet (CAN-Bus) data |
| Center | offset | ± 4mm | Delay | ≤ 0.5μsec. |
| Drive cu | urrent | ≦ 2A | Start-up time | ≦ 2sec.* |
| Operating | gTemperature | 0+50℃ | OperatingTemperature | 0+50°C |
| Protect | ion class | IP 67 | Connector | M12 / Signal: 5 pin (Male), Power: 4 pin (Female) |
| Connec | tor | M12 / Signal : 5 pin (Male), Power : 4 pin (Female) | Protection class | IP 67 |
| Material | Housing | Aluminum+alumite treated (metal) | Material Housing | Aluminum+alumite treated (metal) |
| | Active surface | ABS + PBT (resin) | Active surface | ABS + PBT (resin) |
| Note | | | Note | |

^{*} It is the time of Remote system.

The start-up time of DeviceNet varies with system.

Note

- It is not built in the terminator. Prepare the terminator when necessary.
- The baud rate of RCD33 is 125K ... 500K bps.
- The connector and cable should be prepared separately.

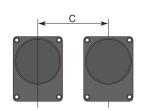
Mounting

In order to avoid influence of surrounding metal, or to avoid mutual influence between parallel-mounted sensors, keep the minimum free zone as described below.

Influence of surrounding metal

Mutual interference

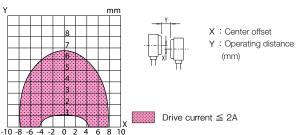




| Type code | A(mm) | B(mm) | C(mm) | |
|----------------|-------|-------|-------|--|
| RCD33T-211-DNC | 50 | 45 | 300 | |
| RCD33E-211-DNC | | | 300 | |

Typical Transmitting Diagram (Supply voltage at 24V / non-flush mount)

RCD33T-211-DNC / RCD33E-211-DNC



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*Specification is subject to change without notice.